

Errata master's thesis

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- p. 8 [...] holomorphic on $U \subseteq \mathbb{C}$ with values in [...] That is, that the limit [...] exists for all $s_0 \in U$.
- p. 8 In the theorem: the statement is not wrong, but $E(w, s) = \phi(s)E(w, 1-s)$ is in line with the definition of ϕ in Theorem 4.10.
- p. 21 Remark 3.13: $k : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$
- p. 41 Item 3.: L^3 should be L_3 .
- p. 49 Below (5.3): it is k which is supported on point pairs at distance at most R , not K . It is $(k \star f)(z)$ which depends only on values of $f(w)$ with $d(z, w) < R$.
- p. 49 Second equation: the first and second convolutions should be on the standard fundamental domain \mathcal{F} , but even then; the last equality is not obvious, because y^s is not Γ -invariant and (4.20) does not apply. We are here implicitly using a ‘local’ version of the Selberg eigenfunction principle: say k is supported on point pairs at distance $\leq R$, so that $(k \star f)(z)$ depends only on values of $f(w)$ for $d(w, z) < R$. Now suppose f is a Laplacian eigenfunction on $B(z, R)$ with eigenvalue $s(1-s)$. (Think $f = [\alpha(y)y^s]_{\mathcal{F}}$.) Under this weaker assumption, does the Selberg eigenfunction principle still hold at z , in the sense that $(k \star f)(z) = \widehat{k}(s)f(z)$? The answer is yes; the proof of the eigenfunction principle (3.31) carries through: if f is a Laplacian eigenfunction in a geodesic ball $B(z, R)$, then so is its radial symmetrization about z in that ball. Because k is supported on point pairs at distance less than R , we conclude using

$$(k \star f)^{\text{rad}}(z) = (k \star f_z^{\text{rad}})(z) = (k \star f(z) \cdot \omega_s(\cdot, z))(z) = f(z) \cdot \widehat{k}(s)$$

as in the proof of (3.31). In the case of $f = [\alpha(y)y^s]_{\mathcal{F}}$, which is a Laplacian eigenfunction for y large, note that we can take the R in

the requirement for the support of k independent of z . Indeed, f is a Laplacian eigenfunction in a ball of radius $\asymp \log y \gg 1$ about z .

p. 60 Proposition 5.40.: see below.

p. 60–61 The end of the proof of Proposition 5.41: We cannot just combine those two envelopes. While $\{f - \text{trunc } f : f \in H(\Gamma, s(1-s))\}$ has a L^2 -holomorphic envelope in $L^2(Y)$ ($Y = \Gamma \backslash \mathbf{H}$), we cannot conclude that it has a L^2 -holomorphic envelope with values in the space of smooth functions W : the dominance principle (5.35) does not apply; we don't have a continuous inclusion $L^2(Y) \rightarrow W$.

To fix this, let X be the sum of $L^2(Y)$ and W . The dominance principle does apply with the natural continuous inclusions $C^\infty(Y) \hookrightarrow X$ and $L^2(Y) \hookrightarrow X$ (if X is given a sufficiently weak topology, such as L^2_{loc}), and (5.41) holds with W replaced by X .

p. 61 Corollary 5.42.: Replace W by X . The proof is more delicate now, as we are no longer working with smooth functions. To begin, we need to extend the system (5.39) to X . This is no problem; it suffices to interpret differential operators in the weak sense. The system we obtain on X still has a unique solution for $\sigma > 1$: by elliptic regularity, a solution f must be a true, smooth function of w . It remains to argue that f is of polynomial growth. By definition of X , f is the sum of a smooth polynomial growth function g and a (automatically smooth) L^2 function h . Write the Fourier coefficients¹ of f (2.24) as

$$\widehat{f}_n(y) = a_n W_{0,s-1/2}(4\pi|n|y) + b_n W_{0,s-1/2}(-4\pi|n|y)$$

for $n \neq 0$. We want to show that the b_n are 0. We have $\widehat{f}_n = \widehat{g}_n + \widehat{h}_n$. Because g is of polynomial growth, so is \widehat{g}_n . Because h is L^2 , it is L^1 and so is \widehat{h}_n :

$$\int_0^\infty |\widehat{h}_n(y)| \frac{dy}{y^2} \leq \int_0^\infty \int_0^1 |h_n(x+iy)| \frac{dx dy}{y^2} < \infty$$

Thus if $b_n \neq 0$, then $W_{0,s-1/2}(-4\pi|n|y)$ is the sum of a polynomial growth function and a L^2 -function. Contradiction.

Finally, we want to show that the a_n are not too large. We show that $|a_n| \ll_\epsilon e^{n\epsilon}$. Indeed, integrating the expression for \widehat{f}_n from ϵ to 2ϵ gives

$$|a_n| \ll_\epsilon \exp(O(n\epsilon)) \int_0^1 \int_\epsilon^{2\epsilon} |f(x+iy)| \frac{dx dy}{y^2}$$

¹It is unfortunate that we (have to?) resort to the Fourier–Whittaker expansion.

where the second factor is finite because f is the sum of a continuous function and a L^2 -function. It follows that f is of rapid decay up to its constant term. But its constant term is a Laplacian eigenfunction, so f is of polynomial growth.

It follows that a solution of the system over X must lie in W , and the uniqueness principle applies.

- p. 61 Corollary 5.43.: Replace W by X ; the proof does not change.
- p. 61 The paragraph before (5.44), and the bottom of the page: “All we know is that they are separately continuous and L^2_{loc} -continuous.” This is not true. We have that $E(w, s)$ is L^2_{loc} continuous (because holomorphic) and smooth for fixed s (by elliptic regularity) so that in particular $E(w, s)$ is a true function, but we do not know that it is continuous for fixed w ! Similarly as in (5.44) we have:

$$\int_{\mathbf{H}} E(w, s) \partial_s \phi(w, s) dw = \int_{\mathbf{H}} \partial_s E(w, s) \phi(w, s) dw$$

where the derivatives are in the L^2_{loc} -sense (simply by the product rule in L^2_{loc}). It follows that $E(w, s)$ is holomorphic in the distributional sense. We show that $E(w, s)$ is (jointly) measurable. It is continuous (hence measurable) for fixed s . For each $n > 0$, divide \mathbb{C} into squares of side length $\frac{1}{n}$ and choose in each square R a point s_R . This defines a sequence $E_n(w, s) = E_n(w, s_{R(s)})$ of measurable pointwise approximations of $E(w, s)$. It converges for fixed s in L^2_{loc} to $E(w, s)$, hence there exists a subsequence which converges almost everywhere to $E(w, s)$. In particular, $E(w, s)$ is measurable. By L^2_{loc} -continuity and Fubini it is jointly L^2_{loc} , and elliptic regularity implies that (after multiplying by a suitable complex polynomial in s) $E(w, s)$ is jointly smooth up to a set of measure 0 in $\mathbf{H} \times U$. (Note here that we don't really need elliptic regularity for overdetermined systems, since $\Delta_{\mathbf{H}} - s(1 - s)$ and Δ_U have the same degree: $E(w, s)$ is also annihilated by their sum, which is elliptic.) Call $F(w, s)$ the function that equals $E(w, s)$ up to a set of measure 0 and which is jointly smooth. We want to show that $E = F$ everywhere. We have that $E - F$ is continuous for fixed s . Suppose it is nonzero at some point (w, s) . Then some local L^2 -norm of $E(\cdot, s)$ is nonzero. By L^2_{loc} -continuity, that local L^2 -norm is bounded away from 0 in a neighborhood of s . This contradicts that $E - F$ is zero a.e.

- p. 81 Proposition B.22, statement 1.: the last statement is not true: boundedness of the partial derivatives does not imply that f is C_b^0 -smooth;

one needs the derivatives to be bounded locally independently of s (e.g. if M is compact). But we don't use this anywhere.